

Effect of Fin Geometry and the Convection Conditions on the Cooling of Electronic Microprocessors

Karanveer Shroff¹, Sunny Kumar Barnwal², Anup Sharma²

¹ Jamnabai Narsee International School, Mumbai, India. 400049

² Department of Mechanical Engineering, Indian Institute of Technology Bombay, Mumbai, India. 400076

Abstract - Microprocessors generate substantial heat due to the high density of transistors and electrical resistance during operation. As transistor sizes decrease and circuit speeds increase, power consumption remains constant, leading to increased heat generation. This heat can cause thermal throttling, reduced efficiency, and potential damage to the microprocessor. Effective thermal management is crucial to maintain performance and longevity. Common cooling methods include air cooling with heat sinks and fans, and liquid cooling systems that use coolant to transfer heat away from the processor. Advanced methods such as thermoelectric cooling modules and materials like graphene are also being explored for their superior thermal conductivity. Barrubeeah et al. (2021) highlight the design and optimization of thermoelectric cooling systems for high-power microprocessors, demonstrating their effectiveness when combined with air-cooled finned heat sinks. Aglawe, Yadav, and Thool (2021) review various cooling technologies, emphasizing the superior heat dissipation capabilities of liquid cooling and its importance for future thermal management. They also note the limitations of air cooling in handling high heat loads, making liquid cooling a more promising solution for advanced microprocessors.

Key Words: Microprocessor, Heat Generation, Thermal Management, Air Cooling, Thermal Conductivity.

1. INTRODUCTION

Microprocessors generate significant heat due to the high density of transistors and the electrical resistance encountered during operation. As transistors become smaller and circuits faster, the power consumption remains constant, leading to increased heat generation¹. This heat can cause thermal throttling, reduced efficiency, and potential damage to the microprocessor². Effective thermal management is crucial to maintain performance and longevity.

To cool down microprocessors, several methods can be employed. Air cooling using heat sinks and fans is the most common approach. Liquid cooling systems, which use coolant to transfer heat away from the processor, are more efficient for high-performance systems^{2,3}. Thermoelectric cooling modules and advanced materials like graphene are also being explored for their superior thermal conductivity.

Thermoelectric Cooling Systems: Barrubeeah et al. (2021) discuss the design and optimization of thermoelectric cooling systems for high-power microprocessors⁴. Their study highlights the effectiveness of thermoelectric modules combined with air-cooled finned heat sinks. The optimized parameters significantly enhance the cooling capacity and efficiency, making it a viable alternative to traditional cooling methods.

Current Cooling Technologies: Aglawe, Yadav, and Thool (2021) review various cooling technologies, including air cooling, liquid cooling, and heat pipes³. They emphasize the importance of liquid cooling for future thermal management due to its superior heat dissipation capabilities. The review also notes the limitations of air cooling in handling high heat loads, making liquid cooling a more promising solution for advanced microprocessors.

Temperature-Based Speed Control: Bai and Ku (2008) explore the use of microcontrollers and IR sensors to control fan speed based on temperature⁵. This method ensures efficient cooling by adjusting the fan speed according to the processor's thermal needs, thereby optimizing energy consumption and maintaining optimal temperatures.

Revolutionary Cooling Inventions: A study published in the Smithsonian Magazine (2020) discusses innovative cooling systems that could revolutionize microprocessor cooling⁶. These systems focus on enhancing thermal conductivity and efficiency, potentially addressing the limitations of current cooling technologies. The research underscores the need for continuous innovation to keep pace with the increasing power and heat generation of modern microprocessors.

In this study, a steady-state finite element analysis was conducted on four different cooling fin geometries. Both natural and forced convection were simulated using appropriate parameters. Forced convection was tested at four different velocities for each fin geometry. Air and water were considered separately as the convecting media in each case. The study highlights the relative differences in temperature drop caused by the various fin geometries. Beyond the surface area, the cross-sectional shape of the fins plays a crucial role in determining the effective heat transfer per fin. The primary focus of the study is on the impact of fin shape on cooling efficiency, rather than the number of fins or

their packing density on the base, which would require a computational fluid dynamics analysis.

2. Model Description

For simulating the cooling process for a microprocessor with fins, a finite element model was created in a commercial solver Abaqus with heat transfer module. A steady state analysis was performed with D3D4 mesh elements.

Steady state analysis was performed. The schematic and fin dimensions for four different variations are given in figure 1. The schematic illustrates four fin design variations, each maintaining consistent base and fin height dimensions. The first two designs feature cylindrical protrusions with radii of 0.002m and 0.004m, respectively. The third design consists of rectangular fins spaced 0.004m apart, while the fourth design has more densely packed rectangular fins with a 0.002m gap. These variations are analysed to assess their thermal performance, as different geometries and spacings can significantly influence heat transfer rates. This

comparison is crucial for optimizing thermal management in engineering applications, ensuring efficient heat dissipation.

The effect of fin geometry was incorporated through Nusselt number calculation⁷. Corresponding heat transfer coefficients were calculated for four different velocities (0.5m/s, 1m/s, 1.5m/s and 2m/s) for the forced convection simulations.

$$Nu = C Re_m Pr^{0.33}$$

$$Re = \frac{vD}{\nu}$$

Initial temperature of the fin and the base was kept at 100°C, which is usually a thermal threshold for daily use microprocessors. The boundary condition at the base was 100°C, with the fins subjected to convection with either of the fluids.

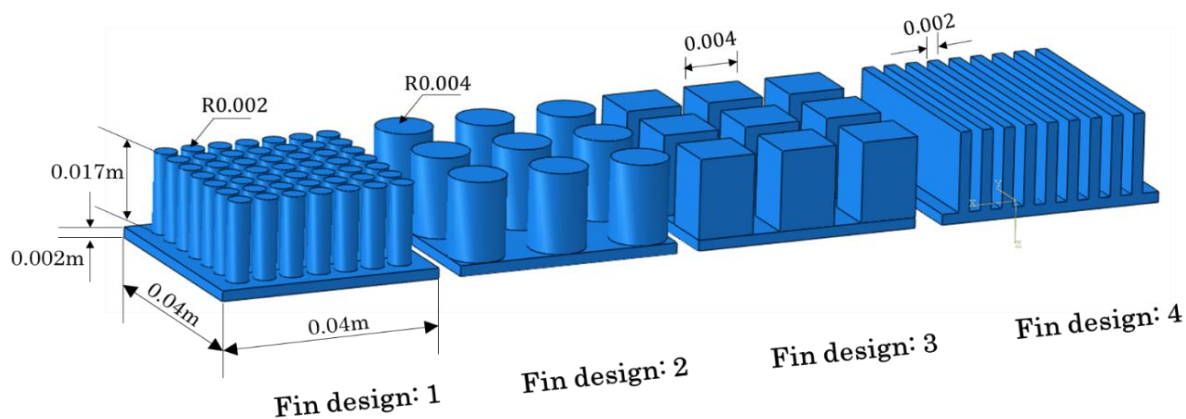


Figure 1: Schematics of four fin design variations used in the study. All the designs have the same overall base and the fin height dimensions. R stands for radius for the first two designs.

3. Results and Discussion

Figure 2 illustrates a steady-state analysis of fin cooling using natural convection with air and water as the convecting media. The fins, made of aluminum, are shown in four different designs. Each design is analyzed for its temperature distribution, with temperatures ranging from 312K to 373K. The top row represents fins in contact with air, while the bottom row shows fins in contact with water. The color gradient indicates the effectiveness of each fin design in dissipating heat. This analysis is crucial for optimizing cooling performance in applications like electronics cooling and heat exchangers.

The clear difference between the two figures is due to a relatively much higher heat transfer coefficient value of water. The difference in thermal profiles of the four geometries is purely due to the available surface area for the coolant. However, the effect of fin geometry can be more utilised through the forced convection mechanism. The natural convection study confirmed the coherence of the current model with physics, so as to move ahead with the further approximated forced convection simulations.

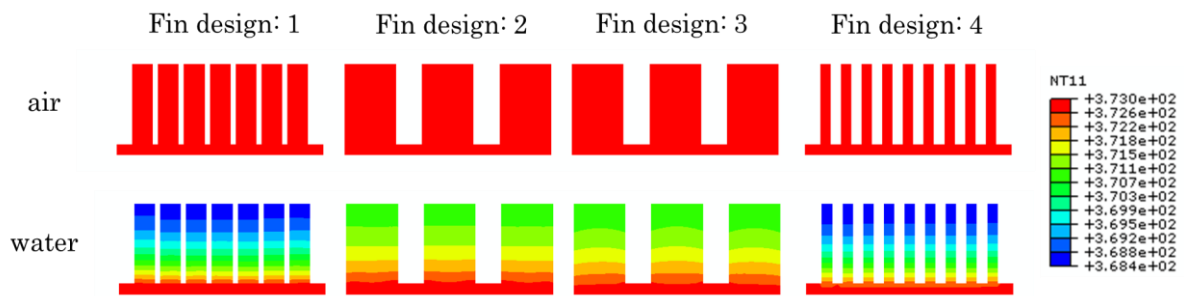


Figure 2: A steady state analysis of fin cooling through natural convection with air and water as the convecting media. The fin material here is aluminium. Temperature is shown in Kelvin.

The figure 3 presents heat transfer coefficients for four different geometries during forced convection. For air as the medium, the coefficients are measured at four different velocities, highlighting how increased airflow impacts heat transfer. For water, the coefficients are measured at a constant velocity of 2 m/s. This comparison is essential for

understanding the efficiency of each geometry in dissipating heat under varying conditions. Such data is crucial in designing thermal systems, ensuring optimal performance and energy efficiency in applications like cooling systems and heat exchangers. This analysis helps engineers select the best geometry and medium for specific cooling requirements.

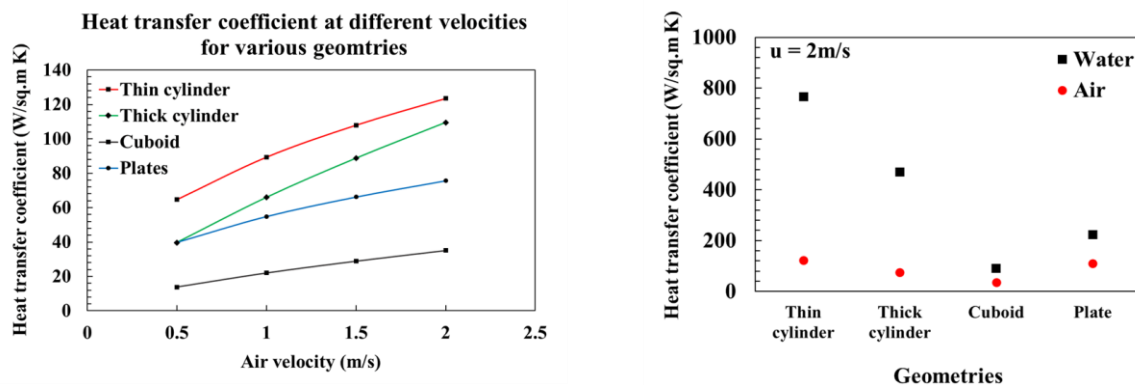


Figure 3: Heat transfer coefficients for the four different geometries during the forced convection with a) air as the medium at four different velocities; and b) with water as the medium at the velocity of 2m/s

Thin cylinders exhibit the highest heat transfer coefficients due to their larger surface area-to-volume ratio, which enhances heat dissipation. The streamlined shape also promotes efficient airflow, reducing thermal resistance and increasing the rate of heat transfer compared to thicker or more complex geometries. The heat transfer coefficient increases with velocity because higher air speeds enhance the convective heat transfer process. Faster-moving air reduces the thermal boundary layer thickness around the object, allowing more efficient heat exchange between the surface and the air. This results in a higher rate of heat transfer as velocity increases.

subsequently Nusselt number. Water, represented by black squares, generally has higher heat transfer coefficients than air (red circles) across all geometries. The thin cylinder exhibits the highest coefficients, followed by the thick cylinder, cuboid, and plate. This indicates that water is more efficient in transferring heat compared to air at the same velocity.

The Nusselt number calculated in the above analysis was dependent on fin dimensions as discussed in the book by Incropera⁷. In Fig. 3b, although Nusselt number constants are same, the variation is through the kinematic viscosity and Prandtl number which affect the Reynolds number and

Water is more efficient at transferring heat compared to air due to its higher thermal conductivity and specific heat capacity. This means water can absorb and transfer more heat energy per unit volume than air. Additionally, water's higher density allows for better contact with the surface, enhancing convective heat transfer and making it a more effective cooling medium.

The cuboid performs worse in heat transfer with both air and water due to its geometric shape, which has a lower

surface area-to-volume ratio compared to cylinders and plates. This reduces the contact area available for heat exchange. Additionally, the flat surfaces and sharp edges of a cuboid can create areas of stagnant fluid flow, leading to less efficient convective heat transfer. These factors combined make the cuboid less effective in transferring heat compared to other geometries.

Fig. 4 displays a comparison of thermal cooling for four geometries at different air velocities. The image presents a detailed steady-state analysis of fin cooling through forced convection at four different air flow velocities.

The 1st fin design having thinner cylinders was found to have higher cooling rate among the four variations. Fin Design 1 shows a relatively uniform temperature distribution at lower air flow velocities, indicating efficient heat transfer. However, as the velocity increases, the temperature gradient becomes more pronounced, with much lower temperature at the end of the fins. Design 2 exhibits a more consistent performance across all velocities. The temperature distribution remains fairly uniform, indicating that this design can handle varying air flow conditions effectively. This makes it a versatile option for applications requiring stable cooling performance. Design 3 shows significant temperature variations at lower velocities, with hotspots indicating less effective cooling. However, at higher velocities, the temperature distribution becomes more uniform, suggesting that this design benefits from increased air flow. This design might be suitable for high-velocity cooling applications.

Analysing the results, it is evident that certain geometries perform better under specific conditions. For example, fins with larger surface areas or more intricate designs may

provide better cooling at lower velocities due to increased surface contact with the air. Conversely, simpler designs might perform adequately at higher velocities, where the increased air flow compensates for the reduced surface area.

The material of thermal fins significantly influences their performance, manufacturing ease, and overall cost. High thermal conductivity materials like copper and aluminum are preferred for thermal fins due to their efficient heat transfer capabilities. Copper, with its superior thermal conductivity, offers excellent heat dissipation but is more expensive than aluminum^{8,9}. Aluminum, while slightly less efficient in heat transfer, is lighter and more cost-effective¹⁰.

Manufacturing ease is another critical factor. Aluminum is easier to machine and form into complex shapes compared to copper, making it a popular choice for manufacturing fins¹¹. Its malleability allows for the production of intricate fin designs that maximize surface area and enhance heat dissipation¹¹. Copper, although more challenging to work with due to its hardness, provides durability and superior thermal performance, which can justify the higher manufacturing complexity in high-performance applications⁹.

Cost considerations are crucial in material selection. Aluminum fins are generally less expensive to produce due to lower material costs and easier manufacturing processes¹⁰. Copper fins, while offering better thermal performance, come at a higher cost both in terms of raw material and manufacturing⁹. Stainless steel, another option, offers good corrosion resistance and durability but has lower thermal conductivity and higher costs compared to aluminum^{8,9}.

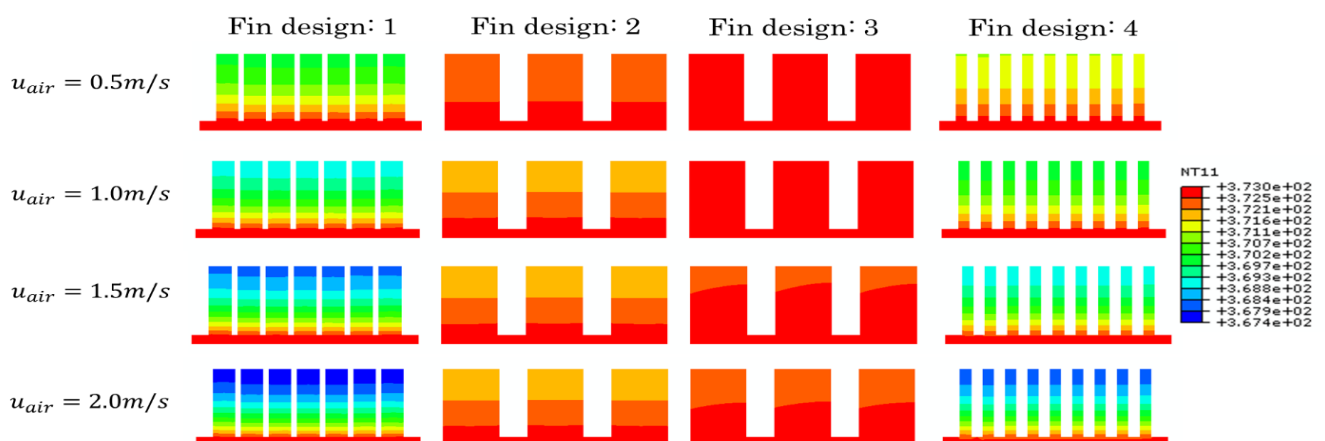


Figure 4: A steady state analysis of fin cooling through forced convection at four different air flow velocities. The effective heat transfer coefficient was varied for every geometry based on the corresponding Nusselt number relations⁷

4. Conclusion

In this study, four different fin geometries were analysed for their cooling efficiency. An approximated simulation for cooling through natural convection was performed using water and air as the cooling media. The results indicated that water provided a higher cooling rate, confirming the model's workability with the approximations (FEM simulations without CFD, using existing empirical formulations). Forced convection simulations were also conducted, incorporating heat transfer coefficients corresponding to shape-dependent Nusselt numbers.

The simulations revealed that the fin design with thinner cylinders exhibited the best cooling rate among the four designs. Thin cylinders have the highest heat transfer coefficients because their larger surface area-to-volume ratio improves heat dissipation. Their streamlined shape also facilitates efficient airflow, lowering thermal resistance and boosting heat transfer rates compared to thicker or more complex shapes. Additionally, the heat transfer coefficient rises with velocity, as higher air speeds enhance convective heat transfer by reducing the thermal boundary layer thickness. These findings highlight the importance of fin geometry in optimizing cooling performance.

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