

# Modeling and Simulation of Resistance Electric Arc Furnace Based on Actual Recorded Data using Artificial Neural Network

Wahyuni Martiningsih<sup>1,2</sup>, Mochamad Ashari<sup>1</sup>, Adi Soeprijanto<sup>1</sup>

<sup>1</sup>Departement of Electrical Eng., Sepuluh Nopember Institute of Tech. Surabaya, Indonesia

<sup>2</sup>Departement of Electrical Eng, Sultan Ageng Tirtayasa University, Cilegon, Indonesia

**Abstract** - This paper presents Artificial Neural Network (ANN) model of electric arc furnace. ANN has a multilayer feed forward network structure and is trained using a back propagation learning rule. The ANN model is used to predict the arc impedance of EAF. The data for training of ANN model uses the measurement data using power quality analysis at side secondary of transformer furnace. Simulation results show that the proposed method is very effective for modeling of electric arc furnace. The performance of best validation reached at epoch 58 and the error is 0.0011961

**Key Words:** electric arc furnace, neural network, back propagation, arc resistance

## 1. INTRODUCTION

Electric Arc Furnace is part of the steel smelting industry which serves to melt the raw materials such as scrap sponge, limestone and other mixed materials into steel[1]. EAF type used is an alternating current electric arc furnace three-phase, which every phase connected with one the electrode. The electrodes produce an electric arc are used as a source of energy for melting[2]. The melting process, electrodes will move up and down through electrode control system to generate stable electric arc, the electrode control system automatically ordered electrode to move up and down to keep gap between the tip of the electrode and material that serves as a load, so that gap between the tip electrode and the charge remained stable according to the reference impedance that have been determined[3]. The distance between the tip electrode and material as a conductor will affect the flow of the electrical current to the electrodes, which in turn affect the electrical arc (arc power) generated. So that when the electric current in the three phase electrodes is stable, the electric arc and the power generated is also stable. Normal operation of the EAF can be divided into two stages, called stage of meltdown and refining. The data in this study were obtained from the data system in the steel industry with loads EAF that seen in figure 1.

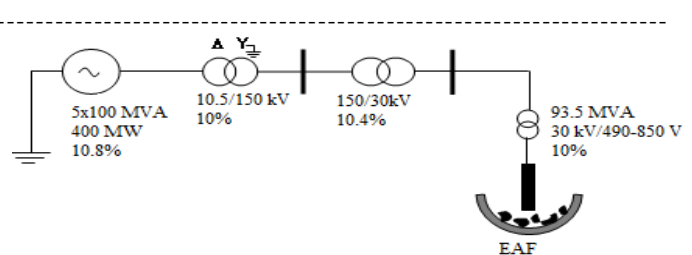


Fig -1: Electrical systems were observed in this study

In this study, EAF connected at 30 kV bus through a transformer furnace with a capacity 30 kV/566 V, 93.5 MVA[4]. Charging is the process of inputting of raw materials of steel that have been placed in a bucket into the electric arc furnace. Charging system of raw materials into an electric arc furnace there are two kinds of charge conventional feeding system and charge continuous feeding system.

The EAFs are non-linear load and the operation of EAF caused power quality problems such as unbalanced voltage and current, voltage flicker and odd and even harmonics. The problem that arises in the EAF needs to be repaired. Researcher have published in remedy of power quality in weak grid system and weak grid characteristics[5][6]. Characteristics response time of EAF have an important role in power quality issues[7].

## 2. ARTIFICIAL NEURAL NETWORK

Artificial Neural networks are information processing paradigm inspired by biological nervous systems, such as our brain[8].

ANN structure is divided into 2 phases:

- Feed forward, if the current propagates information forward and not members output feedback neural network to network input.
- Back forward that if it involves network output feedback input to the network and not just responds to input but also responds to network output is fed into the network input.

The main characteristic of the ANN is the ability to learn. Learning the ANN can be defined as a process of adjusting its parameters (weights interconnect). A desired output depends on the price of interconnection weights are owned by each cell. The learning process can be grouped into two types: supervised learning and unsupervised learning. Supervised learning process requires the desired

output as the basis for changing the weight. While unsupervised learning process, ANN weights will change by itself, in response to input without reference output. Basically back propagation consists of three or more layers (multilayer). Architecture for multilayer back propagation network is shown in Figure 2. In this figure the network has one hidden layer (z units). Unit left layer is input layer which is the only unit in the network that receives input from the outside. The middle layer is the hidden layer that connects the input to the output layer. The hidden layer can amount to one or more layers. The right layer is the output layer. Output unit (unit y) and the unit have a hidden bias. Bias on the output unit behaves the same as the weight on the connections to the output is always 1. The right layer is the output layer. Depicted in Figure 2 only feed forward phase direction. Direction on the back propagation learning phase is the signal sent to the opposite direction.

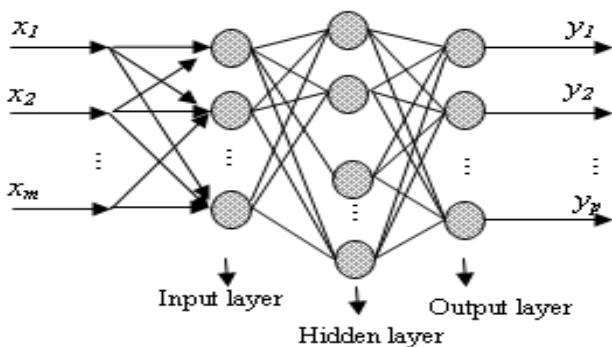


Fig -2: Structure of neural network

### 3. METHODOLOGY

The data used in this study is actual recorded data from plant. Data input are the rms value of current, voltage, and active power. The amount of data used in modeling with the ANN are 15,000 with a composition of 60% data for training, 20% data for testing, and 20% data for validation. The waveform of voltage, current and power like look at Figure 3. The ANN builds using Matlab toolbox.

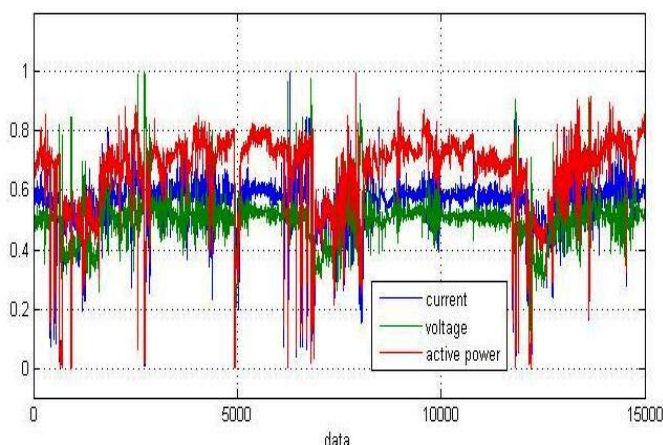


Fig -3: Waveform of neural network input

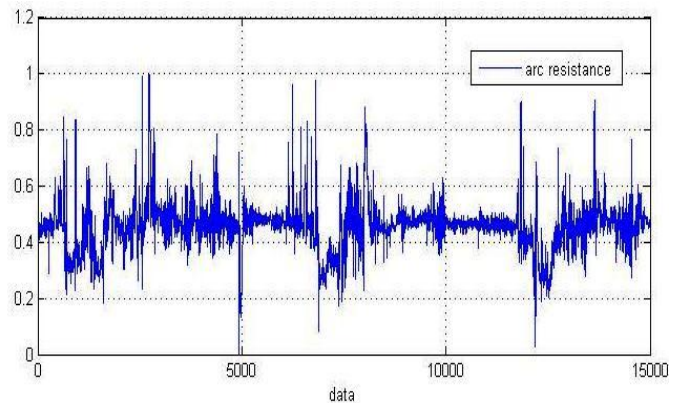


Fig -4: Waveform of neural network target

The data are already in the form of matrix, file names are then given to them for input and target patterns desired. The data are executed in the program back propagation. The data obtained are in the raw form which is still used in the learning process. The data must be in the same range of the activation function, which is usually located between 0 and 1. Therefore, it is necessary to process the raw data by:

$$d_n = \frac{d_x - d_{min}}{d_{max} - d_{min}} \quad (1)$$

Where  $d_n$  is the data have been normalized,  $d_x$  is raw data,  $d_{max}$  is maximum value of the raw data, and  $d_{min}$  Minimum value of the raw data

Figure 5 shown the configuration which used for modeled of EAF, 3 unit inputs, 1 unit of hidden layer with 10 neurons, 1 unit output. The ANN consist of 2 layers i.e. layer 1 and layer 2

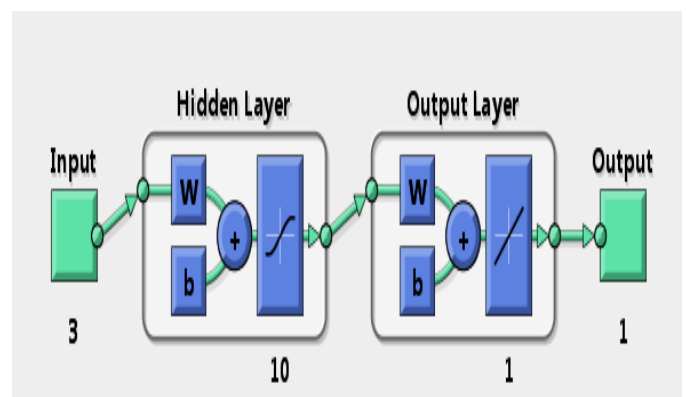


Fig -5: Configuration of neural network for eaf model

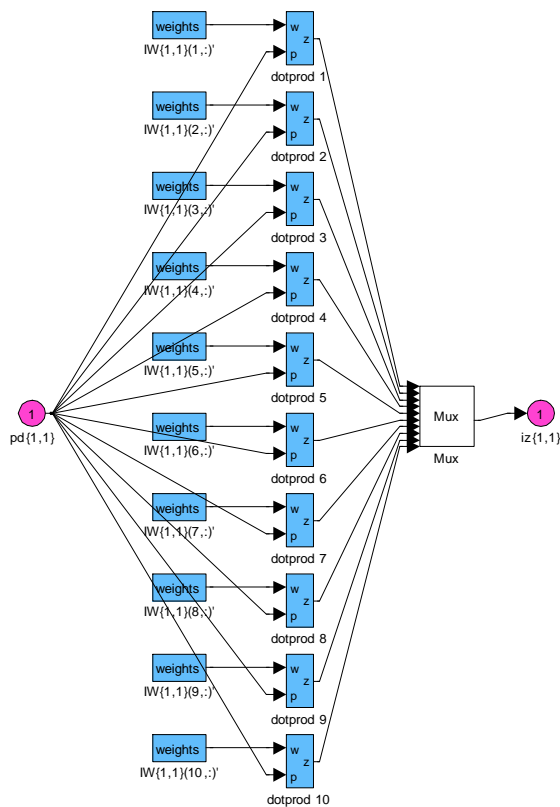


Fig -6: The node of hiddenlayer

#### 4. RESULT AND DISCUSSION

Simulations performed using Matlab 7.6 was applied to the system to provide performance of modeling electric arc furnace. Training network using Levenberg-Marquardtbackprogration and the result shown in table 1.

Table -1: Result of training network

	Sample of data	MSE	R
Training	9000	1.13371e-3	9.26985e-1
Testing	3000	1.23860e-3	9.23115e-1
Validation	3000	1.22798e-3	9.26985e-1

Mean squared error (mse) is the average square different between output and target. Lower values of mse are better, mse close to zero that mean no error. Regression (R) shows the correlation between the output and the target. Value of R close to one that mean a close relationship between output and target. From table 1, the network output and target for the data training were analyzed with linear regression. The correlation coefficient of this model is worth 0.926985 (close to 1) shows good results for the target and network output. Data testing and data validation were analyzed with linear regression too. The correlation coefficient at this model by using the data testing is worth 0.923115 and data validation is 0.926985 shows good results for the target and network output.

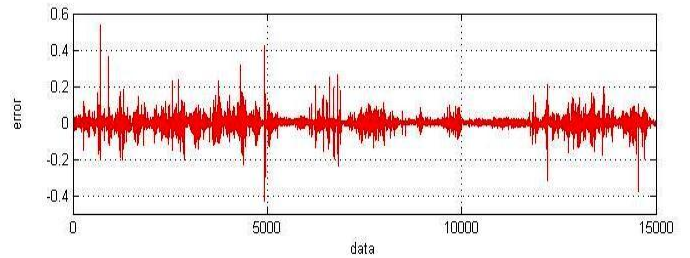


Fig -8: total error

Arc resistance modeling simulation result using artificial neural networks obtained total error (training, testing and validation) as shown in figure 8.

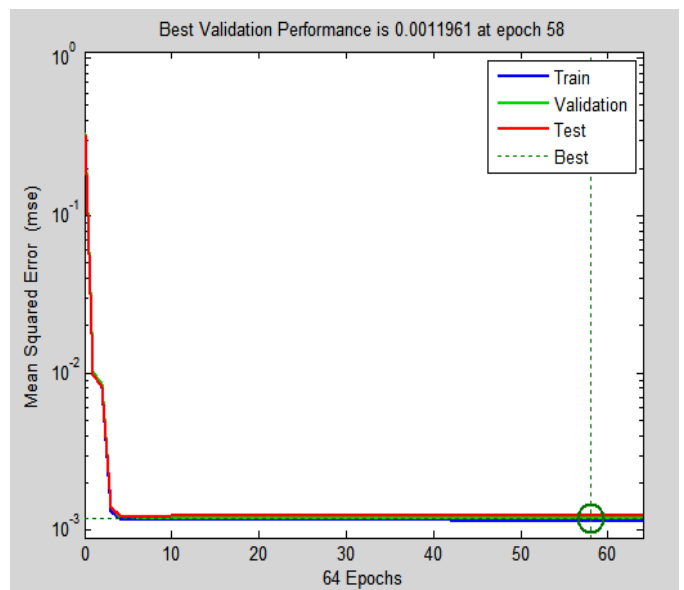


Fig -9: Performance of Epoch

Figure 9 shows the performance of error for the proposed artificial neural network. The model of arc resistance reaches the best validation at epoch 58.

The final result of arc resistance of EAF is illustrated in Figure 10.

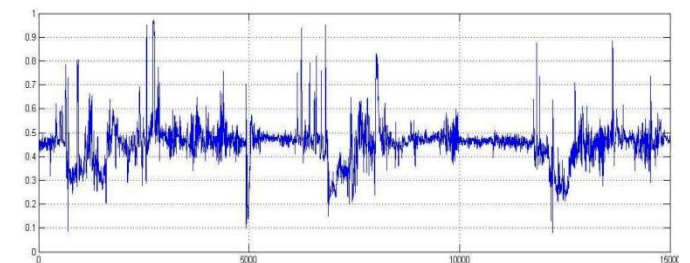


Fig -10: Simulation output of arc resistance

It can be seen that the simulation output of arc resistance obtained for artificial neural network is very similar to the target, as shown in figure 4.

## 5. CONCLUSIONS

Data measurement of EAF could be simulating using Neural Network with 10 hidden layers. Best validation reach is 0.0011961 and at epoch 58. Suggestions of this research are conducted further research using another artificial to get a better performance.

## REFERENCES

- [1] Y.-J. Liu, G. W. Chang, and R.-C. Hong, "Curve-fitting-based method for modeling voltage-current characteristic of an ac electric arc furnace," *Electr. Power Syst. Res.*, vol. 80, no. 5, pp. 572–581, May 2010.
- [2] P. M. Sarma and S. V. J. Kumar, "Electric Arc Furnace Flicker Mitigation in a Steel Plant Using a Statcom," *Int. J. Eng. Sci. Innov. Technol. IJESIT*, vol. 2, no. 1, pp. 227 – 231, Jan. 2013.
- [3] L. Li and Z. Mao, "A direct adaptive controller for EAF electrode regulator system using neural networks," *Neurocomputing*, vol. 82, pp. 91–98, Apr. 2012.
- [4] Wahyuni Martiningsih, Mochamad Ashari, Adi Soeprijanto, and Dian Sawitri, "Sag Voltage Identification on 30 kV Systems Affected By Electric Arc Furnace using Wavelet Transformation Method," *J. Theor. Appl. Inf. Technol.*, vol. 61, no. 2, pp. 352–357, Mar. 2014.
- [5] M. Ashari, C. V. Nayar, and S. Islam, "Steady-state performance of a grid interactive voltage source inverter," 2001, vol. 1, pp. 650–655.
- [6] CV. Nayar and M. Ashari, "Phase Power Balancing of a Diesel Generator using a bidirectional PWM inverter," *IEEE Power Eng. Rev.*, vol. 19 (11), 1999.
- [7] R. Hooshmand, M. Banejad, and M. T. Esfahani, "A NEW TIME DOMAIN MODEL FOR ELECTRIC ARC FURNACE," *J. Electr. Eng.*, vol. 59, no. 4, pp. 195–202, 2008.
- [8] L. H. Tey, P. L. So, and Y. C. Chu, "Neural network-controlled unified power quality conditioner for system harmonics compensation," 2002, vol. 2, pp. 1038–1043.
- [9] Sri Kusumadewi, *Artificial Intelligent (Teknik dan Aplikasinya)*. Jogjakarta: Graha Ilmu, 2003.

## BIOGRAPHIES



Wahyuni Martiningsih, is doctoral student in Institut Teknologi Sepuluh Nopember (ITS), Surabaya, Indonesia. Her research interest include intelligent system application in power system, power electronic and power quality.



Prof. Dr. Ir. Mochamad Ashari, MT, professor at Departement of Electrical Engineering Institut Teknologi Sepuluh Nopember (ITS), Surabaya, Indonesia.

His current interest include application of intelligent systems to power electronic, power quality and renewable energy power source.



Prof. Dr. Ir. Adi Soeprijanto, MT, professor at the Department of Electrical Engineering, Institut Teknologi Sepuluh Nopember (ITS), Indonesia. His current research interests include the application of intelligent technology to power systems operation, management and control.