

# A COMPARATIVE STUDY OF FORCE BASED DESIGN AND DIRECT **DISPLACEMENT BASED DESIGN FOR R.C. BUILDINGS**

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**Abstract** - Traditional codal Force-Based Design (FBD)(IS 1893:2002) method of reinforced concrete buildings subjected to seismic loads, associated with many problems such as, initial-stiffness characterization of structures, inappropriate response reduction factor and calculation of fundamental time period is based on height dependant formula. Codal Force Based Design method cannot design structures for target design objectives under a specified hazard level. These problems resulted in the need for an alternative design approach, which lead to the Performance Based Design (PBD). Direct Displacement Based Design (DDBD) method is based on PBD. Design and analysis is done for reinforced frame buildings of 8, 10, 12, 14 and 16 storey based on following codes IS 456, IS 1893:2002 and the two design approaches are studied. Analysis and design is done using commercial software ETABS 2015. The performance evaluation of buildings designed by FBD and DDBD is done using nonlinear static pushover analysis. The parameters like base shear, storey drift at performance point, consumption of steel and concrete for achieving same performance level are compared for DDBD and FBD. For achieving same performance level of IO, it has been found that the reinforced concrete frame buildings designed by DDBD method is economical than those designed with FBD method under similar conditions of modeling.

Force Based Design(FBD), Direct Kev Words: Displacement Based Design(DDBD), **Pushover** analysis, Seismic method for IS 1893:2002, Reinforced concrete frame building

### **1.INTRODUCTION**

The earthquake forces are most destructive forces among all natural hazards. The application of earthquake forces are random in nature and unpredictable, hence design processes for making structure seismic resistant needs to be clear, definite and effective.

Code design practices have been traditionally based on the Force-Based Design (FBD) (IS 1893:2002) concept, in which individual components of the structure are proportioned for strength such that the structure can sustain the shocks of low intensities without damage, the structure can sustain the shocks of moderate intensities without structural damage and the shocks of heavy intensities without total collapse, on the basis of internal forces computed from the elastic analysis. The inelastic effects are indirectly accounted for by using a Response reduction factor R, which is based on some form of the equal-displacement and equal-energy principles. In the code procedures, an explicit assessment of the anticipated performance of the structure is not done. In the force based codal method of design, the base shear is computed based on perceived seismic hazard level, importance of the building and the appropriate force reduction factor. Then this base shear is distributed over the height of building with some prescribed or estimated distribution pattern. Force Based Design (FBD) suffers from many problems such as the assumed stiffness of the different structural elements, inappropriate response reduction factor and calculation of time period. The emphasis is that, the structure should be able to resist design base shear. Force based design method cannot design structures for target design objectives under a specified hazard level.

Priestley (1993,2000,2003) and other researchers have pointed out that force is a poor indicator of the damage and that there is no clear relationship between the strength and the damage. Hence, force cannot be a sole criterion for design. Further, assuming a flat value of the response reduction factor for a class of buildings is not realistic, because ductility depends on so many factors, such as degree of redundancy, axial force, steel ratio, structural geometry etc. To overcome these flaws in the Force-Based Design (FBD), an alternative design philosophy named "Displacement-Based Design (DBD)" was first introduced by Qi and Moehle (1991), which included translational displacement, rotation, strain etc. in the basic design criteria and then Direct Displacement Based Design (DDBD) was proposed by M.J.N. Priestley (1993) [1]. The Direct Displacement Based Design (DDBD) is based on Performance Based Design (PBD). This philosophy is a very promising design tool that enables a designer to design a structure with predictable performance.

#### 2. DIRECT DISPLACEMENT BASED DESIGN

In the DDBD, the multi degree of freedom structure is converted into equivalent single degree of freedom system. For multi-degree-of-freedom (MDOF) structures the initial part of the design process requires the determination of the characteristics of the equivalent SDOF substitute structure which is shown in fig-1. The required characteristics are Equivalent mass (me), Design displacement ( $\Delta d$ ), and Effective damping ( $\xi_{eq}$ ). When these have been determined, then design base shear of the substitute structure can be determined. The base shear is then distributed between the mass elements of the real structure as inertia forces, and the structure is analyzed under these forces to determine the design moments at locations of potential plastic hinges.

According to Priestley and Pettinga (2005), a full description of the steps needed for applying the DDBD method in the design of reinforced concrete moment resisting frame buildings [1] follows:

#### Step1: Determine design displacement profile ( $\Delta i$ )

The assumed design displacement profile, corresponding to the normalized inelastic mode shape  $\delta_i$  at the design drift limit  $\theta_d$  where *i* = 1 to n storeys, is established using the structural and non-structural deformation limits.

$$\Delta_{i} = \delta_{i} \left( \frac{\Delta_{c}}{\delta_{c}} \right) \boldsymbol{\omega}_{\theta} \qquad \dots (1)$$

Where the normalized inelastic mode shape  $\delta_i$  depends on the height (H<sub>i</sub>) and roof height (H<sub>n</sub>) according to the following relationships:



This normalised inelastic mode shape implies that maximum drift occurs between ground and first floor. So first storey is the critical storey.

 $\omega_{\theta} = 1.15 \cdot 0.0034 H_n \le 1.0 (H_n \text{ in } m) = \text{Drift reduction}$ factor for controlling higher mode effect.

 $\delta_i$  = Normalised inelastic mode shape at mass i

 $\delta c$  = value of normalised inelastic mode shape at critical mass

 $\Delta_{\rm c}$  = Displacement of critical storey =  $\theta_d * H_{\rm c}$ 

 $\boldsymbol{\theta}_d$  = Design drift limit

 $H_c$  = Height of critical or bottom storey = H<sub>1</sub>

H<sub>i</sub> = Height of i<sup>th</sup> storey from base

 $H_n$  = Height of n<sup>th</sup> storey or Top storey height

Step2: Calculate design displacement ( $\Delta d$ ):

$$\Delta_d = \frac{\sum_{i=1}^n (m_i \Delta_i^2)}{\sum_{i=1}^n (m_i \Delta_i)} \qquad \dots (3)$$

Where  $m_i$  =Mass of i<sup>th</sup> floor in kg ,  $\Delta_i$  =Displacement of i<sup>th</sup> floor.

#### Step3: Calculate effective height (He):

$$H_e = \frac{\sum_{i=1}^{n} (m_i \Delta_i H_i)}{\sum_{i=1}^{n} (m_i \Delta_i)} \qquad \dots (4)$$

#### Step4: Calculate yield displacement ( $\Delta_v$ ): $\Delta_v = \theta_v * H_e$ ....(5)

Where,  $\theta_{\rm y}$  = Yeild drift For reinforced concrete frame structure

$$\theta_{\rm y} = 0.5 * \varepsilon_{\rm y} * \frac{L_b}{h_c} \qquad \dots (6)$$

Where, L<sub>b</sub> is the beam span and h<sub>c</sub> is the concrete beam depth.

Step5: Calculate design ductility (µ) and equivalent viscous damping ( $\xi_{eq}$ ):

$$\mu = \frac{\Delta_d}{\Delta_y} \qquad \dots (7)$$





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....(8)

$$\xi_{\text{equi}} = 0.05 + 0.565 * \frac{\mu - 1}{\mu \pi}$$

# Step6: Determine effective time period (T<sub>e</sub>) of substitute structure:

It is the effective time period of the equivalent SDOF system and it is obtained from displacement spectra corresponding to the curve for equivalent damping ( $\xi_{eq}$ ) and the value of design displacement ( $\Delta_d$ ) for IS 1893:2002 [2] as shown in chart-1.

From consideration of the mass participating in the first inelastic mode of vibration, the effective system mass for the substitute structure is,

$$m_e = \frac{\sum_{i=1}^{n} (m_i \Delta_i)}{\Delta_d} \qquad \dots (9)$$
$$K_e = \frac{4\pi^2 m_e}{T_e^2} \qquad \dots (10)$$

#### **Step7: Consideration of P-Δ effect:**

P-Δeffect is considered as per Pettinga and Preistley, (2007) where stability ratio (θPΔ), post yield stability ratio unaffected ( $r_0$ =0.01, assumed) and affected ( $r_p$ ) by P-Δ effect and overall moment (M<sub>B</sub>) are given by following equations,

$$\theta_{P\Delta} = \frac{P\Delta}{V_B H_e} \qquad \dots (11a)$$

$$r_P = \frac{r_0 - \theta_{P\Delta}}{1 - \theta_{P\Delta}} \qquad \dots (11b)$$

$$M_{B} = K_{e} * \Delta_{d} * H_{e} + r_{p} \left[ \frac{2(1-\mu)}{1-r_{p}(\mu-1)} \right] P \Delta_{d} \qquad \dots (11c)$$

Step9: Calculation of design base shear (Vb):

$$V_b = \frac{M_B}{H_e} \qquad \dots (12)$$

**Step10: Distribution of base shear force to floor levels:** The base shear force is distributed to the floor levels in proportion to the product of mass and displacements,

Where, Here V<sub>b</sub>= Design base shear,  $F_t = 0.1 V_b$  at roof level and  $F_t = 0$  at all other floors.

#### **Step11: Calculate the straining actions:**

Using any Finite element software same as ETABS 2015, the building can be modeled then the forces are assigned at each floor level. Finally the corresponding straining actions and design moments at plastic hinge regions can be calculated.

#### **3. NUMERICAL ANALYSIS**

For comparison between the two design method (FBD and DDBD), typical plan as shown in fig-2 is considered. The height of buildings are considered as 8, 10, 12, 14 and 16 – storey having typical storey height 3 m in each building model.



Fig-2: Typical plan view of all building models





The nomenclature of the all building models and target performance level has been listed in Table-1.

#### Table-1: Nomenclature of all building models

Building nomenclature	Design Method	Performance level
ISLS-8, ISLS-10, ISLS-12	IS-1893 (FBD) (Linear static method)	10
ISRS-14, ISRS-16	IS-1893 (FBD) (Response spectrum method)	Ю
DDBD-8, DDBD-10, DDBD-12, DDBD-14, DDBD-16	Direct Displacement Based Design method (DDBD)	Ю

#### Where,

- ISLS-8 = ISLS means building design by Linear Static method of Indian Standard 1893:2002, and numerical figure shows the total number of storey in building like here it is 8 then it shows the building has 8-storey.
- ISRS-14 = ISRS means building design by Response Spectrum method of Indian Standard 1893:2002, and numerical figure shows the total number of storey in building like here it is 14 then it shows the building has 14-storey.
- DDBD-10 = DDBD means building design by Direct Displacement Based Design method and numerical figure shows the total number of storey in building like here it is 10 then it shows the building has 10-storey.
- IO = Immediate Occupancy performance level

### 3.1 Loading data:

Following table-2 shows the loading which considered for analysis of all building models of both design method (FBD and DDBD):

Table -2: Loading data					
(1) Dead load	Typical floor level	At terrace level			
Floor finish	2 kN/m <sup>2</sup>	1.5 kN/m <sup>2</sup>			
Wall load	13 kN/m on all beam	6 kN/m on peripheral beam			
(2) Live load = 2	kN/m² on all f	loor			
(3) Earthquake load	As per Is 1893:2002 [2] Considering, Zone Z = V, Type of Soil = Medium Soil, Importance Factor I = 1 And Response Reduction Factor R = 5.				

### 3.2 Member size of building:

Following table-3 shows the section size of member for all building models.

#### Table-3: Member size of the all building models

		ISLS-8		DDBD-8	
		Width	Depth	Width	Depth
		(mm)	(mm)	(mm)	(mm)
Beam size in X direction		300	600	300	500
Beam si	ze in Y direction	300	650	300	600
column	In 4 to 8 storey	600	600	400	400
size	In 1 to 3 storey	650	650	450	450
		ISLS	5-10	DDBD-10	
Beam si	ze in X direction	300	700	300	500
Beam si	ze in Y direction	300	700	300	600
column	In 4 to 10 storey	600	600	450	450
size	In 1 to 3 storey	700	700	550	550
		ISLS	5-12	DDBD-12	
Beam si	ze in X direction	300	700	300	500
Beam si	ze in Y direction	300	750	300	600
	In 9 to 12 storey	550	550	450	450
column	In 6 to 8 storey	650	650	450	450
size	In storey 5	650	650	550	550
	In 1 to 4 storey	750	750	550	550
		ISRS-14		DDB	D-14
Beam si	ze in X direction	300	750	300	550
Beam si	ze in Y direction	300	750	300	650
column	In 10 to 14 storey	550	550	450	450
size	In 5 to 9 storey	650	650	500	500
	In 1 to 4 storey	750	750	600	600
		ISRS	S-16	DDB	D-16
Beam size in X direction		300	750	300	550
Beam size in Y direction		300	750	300	650
	In 11 to 16 storey	550	550	450	450
column	In 5 to 10 storey	650	650	500	500
size	In 3 to 4 storey	700	700	600	600
	In 1 to 2 storey	800	800	600	600



#### 3.3. Parameters for pushover analysis:

For an evaluation of seismic performance, the mathematical models developed are subjected to push over analysis as per FEMA-440 [3] provisions using ETABS 2015 software. Default Plastic hinges of four types are available in the software. Out of them, P-M-M types of hinges are defined based on FEMA-356 [4] for all column elements. For all beam elements, flexural plastic hinges M3 are defined based on FEMA-356 [4]. The members of the frame are designed for standard load of combination as specified in IS 456:2000 [5] and IS 1893:2002 [2] for all FBD building models. In DDBD, Expected material strength used in design stage and Load combinations is used as, (1) DL + IL (2) DL + IL ± EL (3) DL ± EL and hinge locations [6] of user defined hinge is considered as per fig-3 and following equations:



Fig-3: Hinge locations at ends of beam and column [6]

$l_1 = 0.5^* L_P$	(14a)
$l_2 = H_{beam} - 0.5 * L_P$	(14b)
$l_3 = 0.5 * H_{column} - 0.5 * L_P$	(14c)

Where,

 $L_p$  = It is Plastic hinge length = 0.5\*H (Park and Paulay [7]) H = Section depth

Hbeam = Depth of beam

Hcolumn = Depth of column

 $l_1$  = It is plastic hinge location at i end of column

 $l_2$  = It is plastic hinge location at j end of column

 $l_3$  = It is plastic hinge location at i and j end of beam

Typical drift value for various performance levels are given in following table-4 as per FEMA 356:

#### Table -4: Drift value for various performance level

Performance level	Drift value
Immediate occupancy (IO)	1 %
Life safety (LS)	2 %
Collapse prevention	4 %

#### **4. ANALYTICAL RESULTS**

Analysis and design results of all building models for both methods (FBD and DDBD) are discussed and to compare both methods in such type of parameters like, Base shear, Storey drift and Consumption of steel and concrete at performance point.

#### 4.1 Comparison between base shear calculated by **FBD and DDBD method:**

The base shear calculated for all FBD building models by FBD method according to IS 1893:2002 is compared with base shear calculated using DDBD method as described in section 2 for all DDBD building models.

Table-J. Calculated base silear							
Building	By FBD (kN)	By DDBD (kN)					
Storey-8	3970	2695					
Storey-10	4604	2762					
Storey-12	4693	3062					
Storey-14	4624	3386					
Storey-16	4739	3858					

Comparison between base shear calculated by

Table F. Calculated bace cheer



#### Chart-2: Comparison between base shear calculated by FBD and DDBD method

Table-5 shows the total base shear for FBD and DDBD building models. It is observed that total base shear calculated by DDBD method is 26.7%, 34.3%, 28.7%, 26.8% and 18.6% less for 8, 10, 12, 14 and 16-storey respectively compared to FBD building models.

#### 4.2 Seismic performance of all FBD and DDBD building models:

All FBD and DDBD building models of 8,10,12,14 and 16 storey building are analysed and design in ETABS 2015 and then seismic performance evaluated of all building model by nonlinear static pushover analysis in ETABS 2015. For demand curve we have considered Response spectrum of IS 1893:2002 for medium soil, zone V and Design Basis Earthquake (DBE). Following table 6 shows the seismic performance of all building models.



**Building model** 

Direction

ISLS-8

DDBD-8

ISLS-10

DDBD-10

ISLS-12

DDBD-12

ISRS-14

DDBD-14

ISRS-16

DDBD-16

Applied base shear V (kN)		Base shear at performance point (kN)		Displacement (mm)		Effe Dampi	ctive ng (%)	No Hinge: lev	. of s in IO /el
Х	Y	Х	Y	Х	Y	Х	Y	Х	Y
3970	3970	7097	7186	91.6	92.2	5.02	5.05	94	77
2695	2695	2540	2768	121.2	108.5	6.77	6.52	208	183
4604	4368	8386	7797	100.2	108.6	5.01	5.01	120	60
2762	2762	2597	2823	137.3	121.7	6.99	7.11	266	231

122.8

167.5

128.2

175.8

140.8

200.1

122

146.7

138.6

157.9

154.3

179.9

8371

2983

7055

3232

6845

3601

8648

2790

7353

3033

7085

3390

Table-6: Pushover results of all building models at performance point

4452

3062

4386

3400

4514

3921

From table-6, the following points can be concluded:

1. It is observed that effective damping of all FBD building models is nearer to 5% in both directions so its performance is close to yield point it means that extra capacity is available in non-linear region. Hence, FBD method gives conservative design.

4693

3062

4624

3386

4739

3858

- It is observed that base shear at performance point 2. is more in FBD building models than in DDBD building models. It may be noted that FBD building models are designed with partial load factor and material safety factor so that actual steel is provided for higher force. DDBD is a kind of performance based design hence, DDBD building models are designed without load factor and material safety factor so that its base shear less than in FBD building models at performance point.
- It is observed that all hinges remain in IO state for 3 both FBD and DDBD building models.

5.13

6.44

5.28

6.62

5.27

6.09

5.03

6.64

5.22

6.7

5.25

6.19

144

286

228

296

256

302

168

275

196

302

239

301

As the number of storey increases, the difference in 4 number of hinges formed in FBD and DDBD models at performance point decreases. It means that DDBD method converges to FBD method for higher storey buildings.

#### 4.3 Comparison of consumption of steel and concrete between all FBD and DDBD building models:

A comparison of consumption of steel and concrete between all FBD and DDBD building models at performance point is done.

Following table-7 shows the comparison of consumption of steel and concrete in FBD and DDBD building models:

Table-7: Comparison of consumption of steel and concrete in FBD and DDBD building models							
Building model	Steel consumption in tonne	Difference in % Of consumption of steel	Concrete consumption in m <sup>3</sup>	Difference in % Of consumption of concrete	Achieved performance level		
ISLS-8	57.48	<b>F</b> 4 0	439.65	24.4	10		
DDBD-8	26.31	54.2	288.45	34.4	IO		
ISLS-10	76.8	F 4 7	596.4	20.2	IO		
DDBD-10	34.82	54.7	421.5	29.3	10		
ISLS-12	89.95	40 5	753.6	21.0	IO		
DDBD-12	45.42	49.5 514.2		31.8	10		
ISRS-14	100.96	42.7	888	26 5	10		
DDBD-14	57.87	42.7	652.65	26.5	10		
ISRS-16	114.25	26.0	1008.6	26 5	10		
DDBD-16	72.09	36.9	741.3	26.5	10		

Following points are observed from table 7:

- 1. For achieving similar performance as IO level, buildings designed with DDBD method consumes 54.2%, 54.7%, 49.5%, 42.7% and 36.9% less steel for 8,10,12,14, and 16 storey building respectively than those designed with IS 1893:2002 method (FBD). The concrete consumption is found to be 34.4%, 29.3%, 31.8%, 26.5% and 26.5% less for 8,10,12,14, and 16 storey building respectively than those designed with IS 1893:2002 method (FBD).
- **2.** It is also observed that as number of storey increases difference in consumption of steel and concrete decreases, it means that DDBD method converges to FBD method for higher storey buildings.

# 4.4 Comparison of storey drift at performance point for all FBD and DDBD building models:

For comparison of storey drift at performance point for FBD and DDBD method, here comparison of the storey drift in X direction between all building models of FBD and DDBD method at performance point is presented.

Following charts shows the storey drift at performance point for all building models.



Chart-3: Storey drift at performance point for 8storey building







Chart-5: Storey drift at performance point for 12storey building



Chart-6: Storey drift at performance point for 14storey building





Chart-7: Storey drift at performance point for 16storey building



Chart-8: Maximum storey drift at performance point between FBD and DDBD building models

From chart-3 to 8, following points can be concluded:

- Charts-3, 4, 5, 6 and 7 shows that storey drift 1 increases up to 4th storey in ISLS-8 and DDBD-8, 5th storey in ISLS-10 and DDBD-10, 6th storey in ISLS-12 and 7th storey in DDBD-12, 8th storey in ISRS-14 and DDBD-14, 8th storey in ISRS-16 and 9th storey in DDBD-16 and then decreases as number of storey increases, thus maximum storey drift occurs at mid height of the building.
- 2 From chart-8, the maximum storey drift values for FBD is lesser than that of the DDBD comparing on

their respective storey. This decrease in drift indicates that the FBD structure is more rigid as compared to DDBD structures. For DDBD building models the maximum storev drift at performance point is less than 1% which is well within permissible values.

# **5. CONCLUSION**

By comparing various parameters like base shear, storey drift, consumption of steel and concrete at performance point, for all FBD and DDBD building models following conclusions can be drawn:

- Direct Displacement Based Design gives lower base shear than Force based method (IS 1893:2002). Base shear obtained by DDBD is 26.7%, 34.3%, 28.7%, 26.8% and 18.6% less for 8, 10, 12, 14 and 16storey respectively compared to Force Based Method (IS 1893:2002). These results shows that Force based method (IS 1893:2002) is conservative in designing medium rise buildings.
- It is observed that as number of storey increases, difference in base shear obtained by FBD and DDBD method decreases. It means that DDBD method converges to FBD method as number of storey increases.
- For achieving same performance level, reduction in section size as well as percentage reinforcement in Direct Displacement Based Design is observed. It can be concluded that buildings, designed with Direct Displacement Based Design are economical than those designed with the Force Based Design method (IS 1893:2002).
- Non-linear static push-over analysis is carried out for evaluation of both methods. The performance of all the frames designed by Direct Displacement Based Design and Force Based Design method are satisfactory.

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