

Advancement of the Adjustable and Modest 3D Printed Prosthetic Arm Utilizing Electromyography

B. Affrudeen¹, R. Abinaya¹, B. Harish¹, V. Gunaseelan¹, Dr. B. Sivasankari²

¹-UG Student, SNS College of Technology, Coimbatore.

²-Associate Professor, SNS College of Technology, Coimbatore.

Abstract - In organ transplantations, the deficiency for the donor is a noteworthy clinical issue all through the world. Also, high risks happen when we favor conventional strategies that may incorporate higher intricacy, auxiliary wounds, and constrained source donors. Because of inborn inconsistencies, incidental injury, individuals are enduring for some time in the past. This issue of donor deficiency can be solved with the help of implementing 3D printing in the medical field. In this paper, an adjustable 3D printed prosthetic arm which works with the help of a signal called electromyography (EMG) is designed and its statistical working is established. This arm helps an amputated person to be free from the amputation and independent in most circumstances.

Keywords: Amputation, Electromyography, Prosthetics, 3DPrinting, Upper limb.

1. INTRODUCTION

3D printing is a procedure of creating three dimensional solid substances from a computerized document. The production of a 3D printed object is achieved utilizing added element forms. By additive manufacturing, an object is produced by depositing down consecutive layers of material until the object is produced. 3D printing advancement is depended upon to disentangle the limitations that are unavoidably experienced while using standard methodologies by melding the modified improvement of human bionic tissue or organs. Ongoing insights study demonstrates 25 percent of the universe's populace experience a few forms of disabilities. From a recent survey, it is found that out of the universe's population around thirteen million persons suffer from amputation in which half of the cent is arm amputees.

1.1 Arm Amputation

Arm amputees are person without an arm or a part of it which may be lost due to any mishaps. The two situations are enduring while at the same time doing their day by day life routine without anyone else and they need help from others. There are distinctive solutions for the assistance of the amputees, be that as it may be, they are either being unbelievably costly not every person can bear, hard to introduce and keep up, or it might require surgeries for this situation it depends on the nerves which now and again may be harmed. Each existing solution has favorable circumstances and burdens. Upper limb amputation happens

at a pace of 5.3 people per lakh individuals; finger removals are the most well-known 3.5 people per lakh.

2. METHODOLOGY

One of the arrangements for arm amputees can be made with the help of a prosthetic arm. The prosthetic arm should be evaluated and resolved to the unfortunate victim's needs. The subsequent course of action is the surgical appendages, where the patient will have surgery to have another arm. The subsequent arrangement is nearly costlier. A couple of issues may happen because of the surgical arm. The prosthetic arm has fewer issues when it appeared differently concerning the surgical arm.

Prosthetic arm avoids various restorative issues that may result from the clinical methodology technique, There are various strategies to screen and control a mechanical arm where one framework is to use an EEG contraption (a headset), which assists with recording the signs from the mind when the individual is thinking about an action or realizing an outward facial appearance. The EEG will examine the signs acquired and a short time later believer them to directions and forward them to the arm. The subsequent framework is to use muscle movement sensors, which are known as electromyography (EMG) sensors. The EMG signal which is gotten from the electrical potential delivered by the muscle cells can be examined to recognize restorative varieties from the standard, incitation level, or the selection demand. EMG signal is to be set up for numerous hand motions and advancement confirmation.

The departure of the prosthetic arm accompanies both enthusiastic and functional impairment in this way making the structure procedure significant not simply as far as solace yet appearance too. The rear block diagram (Fig -1) shows the way how a coarse EMG signal is first preprocessed for the further working of the prosthetic arm.

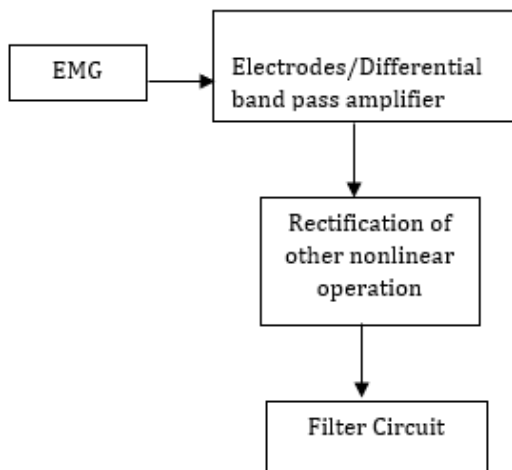


Fig -1: Preprocessing of EMG Signal

3. PROPOSED SYSTEM

The reference electrode is in touch with the muscle from which the EMG signal is obtained and then amplified by an amplifier. The Amplified EMG signal is then filtered and then extracted as a digital signal which is further classified into various forms. It is noteworthy that this system is conservative and constrained by internal sources.



Fig -2: 3D Printed Prosthetic Arm Hardware Model

Using a divider power supply is exact for looking at and troubleshooting yet a prosthetic arm ought to be constrained by a source an amputee can move without a lot of a stretch bear. Servo engines use a great deal of current during the action. Nonessential batteries would not be an OK game plan since the servos would drain power too speedy hugeness they would be displaced frequently. Lithium Polymer (LiPo) batteries offer a high imperativeness thickness and are battery-powered. There is a trade-off between the life of the battery and its size. Ideally, we may need the arm to have the

alternative to continue running for a couple of hours without standing by to be stimulated. The workflow of the 3D printed prosthetic arm is described via the following block diagram (Fig -3).

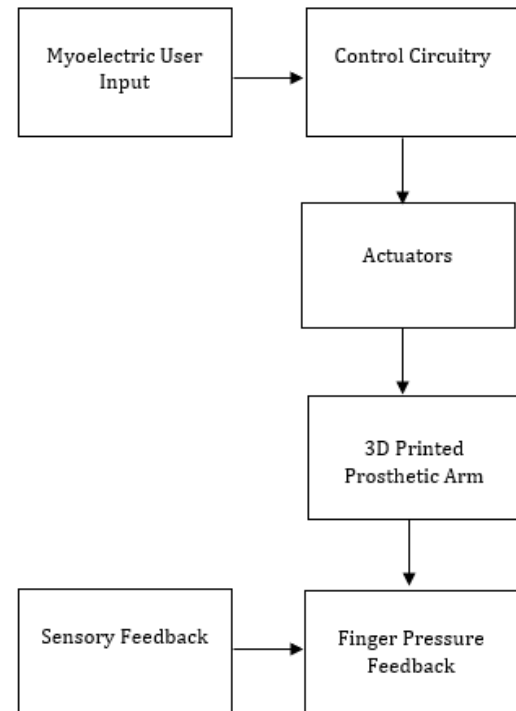


Fig -3: Workflow of the Prosthetic Arm

4. RESULT AND ANALYSIS

Research work is implemented and intended to the victim to check the controls and proper function of the arm. The victim is subjected to do various basic daily activities like holding an object.

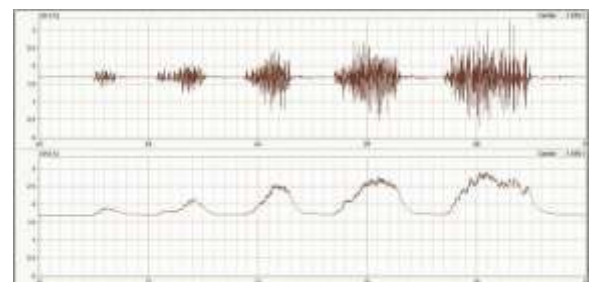


Fig -4: EMG Signal Output

The effects of individual action examination are 100 percent resolution rate. Figure 4 shows the prevailing EMG wave. Figure 5 shows the MATLAB output of various forms of EMG signal.

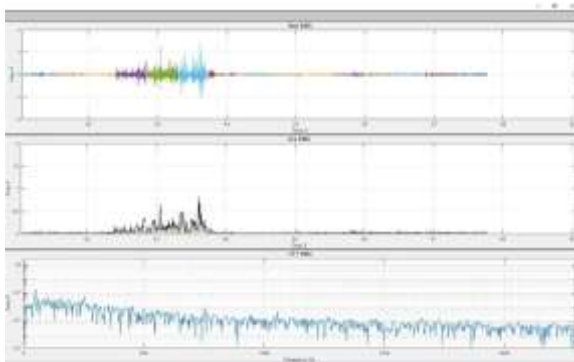


Fig -5: Various Forms of EMG Signal.

5. CONCLUSION

The prosthetic arm which is 3D printed by implementing the process called additive manufacturing is intended to be moderate (economical) and lightweight to furnish the amputee with comfort and independence for the daily activities of life. Approximated estimate of the prosthetic arm utilizing electromyography is tabulated as follows.

Table -1: Estimate of the 3D Printed Prosthetic Arm

S.no.	Components Description	Cost
1	1 kg filament ABS	\$15
2	2 cell LiPo Battery	\$20
3	6 x Servomotor	\$70
4	EMG sensor (muscle sensor)	\$80
5	Miscellaneous	\$30
6	Total	\$215

This research work represents how the EMG signal is utilized for establishing a prosthetic arm employing the AD8232 sensor to sense the muscle contraction. Later, the arm will be examined on furthermore discussions with numerous arm amputee problems. Moreover, the arm will include embedded sensors on the palm and tip of the finger to enable the outputs such as warmth to give additional input of the victims encompassing parts. The hardware analysis of the electromyogram is obtained in order to check with the control of the arm.

6. REFERENCES

[1]. J. Zhao, Z. Xie, L. Jiang, H. Cai, H. Liu and G. Hirzinger. "A Five-fingered Underactuated Prosthetic Hand Control Scheme". IEEE/RAS-EMBS International Conference on Biomedical Robotics and Biomechatronics. BioRob 2006. IEEE Explore Digital Library. Pisa, Italy, 20-22 February 2006; pp.: 995 to 1000.

[2]. Y. Jiang, S. Sakoda, S. Hoshigawa, H. Ye, Y. Yabuki, T. Nakamura, M. Ishihara, T. Takagi, S. Takayama and H. Yokoi. "Development and evaluation of simplified EMG prosthetic hands". IEEE International Conference on Robotics and

Biomimetics, ROBIO'14. IEEE Explore Digital Library. December 2014.

[3]. Angkoon Phinyomark, Pornchai Phukpattaranont, and Chusak Limsakul, "Feature reduction and selection for EMG signal classification," Expert Systems with Applications, vol. 39, no. 8, pp. 7420-7431, 2012.

[4]. Orgil Chinbat; Jzau-Sheng Lin "Prosthetic Arm Control by Human Brain" 2018 International Symposium on Computer, Consumer and Control (IS3C).

[5]. Sherif Said, Samer AlKork, Amine Nait-Ali, "Wearable Technologies in Biomedical and Biometrics Applications," in Biometrics under Biomedical Applications, Springer, 2019, p. Chapter 10.

[6]. M.D. Azulay, M.I. Pisarello and J.E. Monzón. "Electromyographic control of a robotic arm for educational purposes". 3rd Middle East Conference on Biomedical Engineering, MECBME'16. IEEE Explore Digital Library. 6-7 October 2016, Beirut, Lebanon; pp.: 129 to 132.

[7]. Y. Mangukiya, B. Purohit and K. George, "Electromyography (EMG) sensor controlled assistive orthotic robotic arm for forearm movement," 2017 IEEE Sensors Applications Symposium (SAS), Glassboro, NJ, pp. 1-4, 2017.

[8]. Y. She, C. Li, J. Cleary, and H. Su, "Design and Fabrication of a Soft Robotic Hand with Embedded Actuators and Sensors," ASME J. Mechanisms Robotics, Vol. 7 (2), pp. 021007-021007-9, 2015.

[9]. Ramya, E. Affrudeen, B. Abinaya, R. "Smart City Implementation Models Based on IOT Technology", JETIR September 2018, Volume 5, Issue 9, 2018.

[10]. S. Mallik and M. Dutta, "A study on control of myoelectric prosthetic hand based on surface EMG pattern recognition", International Journal of Advance Research in Science and Engineering, vol. 06, issue 07, pp. 635-646, 2017.

[11]. A. J. Young, L. H. Smith, E. J. Rouse and L. J. Hargrove, "Classification of simultaneous movements using surface EMG pattern recognition," IEEE Transactions on Biomedical Engineering, vol. 60, pp. 1250-1258, 2013.

[12]. R. Lakshmana Kumar, C. Suresh, B. Affrudeen, R. Abinaya, "Smart Shopping Cart Method For Reducing Man Power In Departmental Stores", Journal of Applied Science and Computations, Volume VI, Issue I, January/2019 ISSN NO: 1076-5131.

[13]. A. Suberbiola, E. Zulueta, J. M. Lopez-Guede, Ismael Etxeberria-Agiriano, and M. Graña. "Arm orthosis/prosthesis movement control based on surface EMG signal extraction." International journal of neural systems 25, no. 03 (2015).

[14]. G. N. Mahanth, B. C. Sachin, J. S. Kumar, S. N. Vinayand V. P.Sompur, "Design of Prosthetic Finger Replacements Using SurfaceEMG Signal Acquisition," 2014 Texas Instruments India Educators'Conference (TIIEC), Bangalore, pp. 100-104, 2014.

[15]. H. Daley, K. Englehart, L. Hargrove, and U. Kuruganti, "High density electromyography data of normally limbed and transradial amputee subjects for multifunction prosthetic control," J Electromyogr Kinesiol, vol. 22, pp. 478-84, Jun 2012.

[16]. Alejandro Calzades; Jean Pazos; Diego Benítez, "On the use of 3D printing technology towards the development of a low-cost robotic prosthetic arm", 2017 IEEE International Autumn Meeting on Power, Electronics and Computing (ROPEC).

[17]. F Rengier, A Mehndiratta, H von Tengg-Kobligk, CM Zechmann, R Unterhinninghofen, HU Kauczor, FL Giesel, "3D printing based on imaging data: review of medical applications,"International Journal of Computer Assisted Radiology and Surgery, vol. 5, Issue 4, pp 335-341, 2010.

[18]. Narjes Meselmani, Mostafa Khayzat, Khaled Chahine, Milad Ghantous, Mohamad Hajj-Hassan, "Pattern recognition of EMG signals: Towards adaptive control of robotic arms" IEEE International Multidisciplinary Conference on Engineering Technology (IMCET), 2016.

[19]. A. Gupta, "Analysis of Surface Electromyogram Signals during Human finger movements," International Journal of Engineering Research and Development, vol. 1, pp.1518, June 2012.

[20]. R. Chowdhury, M. Reaz, M. Ashrif, A. Bakar, K. Chellappan, T. Chang, "Surface Electromyography Signal Processing and Classification Techniques," Sensors, vol. 13, pp. 12431-12466, September 2013.